

view_frames Result
Recorded at time: 1587038735.309

map

odom

epuck2_robot_0/base_link

epuck2_robot_0/body_top

epuck2_robot_0/left_wheel

epuck2_robot_0/right_wheel

epuck2_robot_0/base_prox0

epuck2_robot_0/base_prox1

epuck2_robot_0/base_prox2

epuck2_robot_0/base_prox3

epuck2_robot_0/base_prox4

epuck2_robot_0/base_prox5

epuck2_robot_0/base_prox6

epuck2_robot_0/base_prox7

epuck2_robot_0/base_laser

epuck2_robot_0/base_dist_sens

Broadcaster: /slam_gmapping
Average rate: 20.204 Hz
Most recent transform: 1587038735.336 (-0.026 sec old)
Buffer length: 4.900 sec

Broadcaster: /epuck2_robot_0
Average rate: 11.047 Hz
Most recent transform: 1587038735.240 (0.069 sec old)
Buffer length: 4.798 sec

Broadcaster: /epuck_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1587038735.309 sec old)
Buffer length: 0.000 sec

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