

view\_frames Result  
Recorded at time: 1587038797.969

map

odom

epuck2\_robot\_0/base\_link

epuck2\_robot\_0/body\_top

epuck2\_robot\_0/left\_wheel

epuck2\_robot\_0/right\_wheel

epuck2\_robot\_0/base\_prox0

epuck2\_robot\_0/base\_prox1

epuck2\_robot\_0/base\_prox2

epuck2\_robot\_0/base\_prox3

epuck2\_robot\_0/base\_prox4

epuck2\_robot\_0/base\_prox5

epuck2\_robot\_0/base\_prox6

epuck2\_robot\_0/base\_prox7

epuck2\_robot\_0/base\_laser

epuck2\_robot\_0/base\_dist\_sens

Broadcaster: /slam\_gmapping  
Average rate: 20.203 Hz  
Most recent transform: 1587038797.994 ( -0.025 sec old)  
Buffer length: 4.950 sec

Broadcaster: /epuck2\_robot\_0  
Average rate: 50.974 Hz  
Most recent transform: 1587038797.747 ( 0.222 sec old)  
Buffer length: 4.512 sec

Broadcaster: /epuck\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1587038797.969 sec old)  
Buffer length: 0.000 sec

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Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1587038797.969 sec old)  
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Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1587038797.969 sec old)  
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Broadcaster: /epuck2\_robot\_0  
Average rate: 51.418 Hz  
Most recent transform: 1587038797.747 ( 0.222 sec old)  
Buffer length: 4.512 sec

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